

On $\overset{0}{g}$ - Homeomorphism in topological spaces

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(Acceptance Date 8th March, 2013)

Abstract

In this paper we introduce a new class of closed maps namely $\overset{0}{g}$ -closed maps which settled in between the class of g^* -closed maps¹² and the class of gs -closed maps¹². We also introduce and study new class of homeomorphisms called $\overset{0}{g}$ -homeomorphisms and $\overset{0}{g}^*$ -homeomorphisms. Further we show that the set of all $\overset{0}{g}^*$ -homeomorphisms form a group under the operation composition of maps.

Key Words : $\overset{0}{g}$ -closed maps; $\overset{0}{g}^*$ -closed maps; $\overset{0}{g}^*$ -homeomorphisms.

1. Introduction

The notion homeomorphism plays an important role in topology. A homeomorphism between two topological spaces X and Y is a bijective map $f : X \rightarrow Y$ when both f and f^{-1} are continuous. Malghan¹⁶ and Devi *et al.*⁸ introduced the concept of generalized closed maps and semi generalized closed maps respectively in topological spaces. Veera kumar introduced ψ -closed maps in topological spaces. In this paper we introduce a new class of closed maps namely $\overset{0}{g}$ -closed maps and

then introduce and study $\overset{0}{g}$ -homeomorphisms and $\overset{0}{g}^*$ -homeomorphisms in a topological space.

We also prove that the set of all $\overset{0}{g}^*$ -homeomorphisms forms a group under the operation composition of functions.

2. Preliminaries :

Throughout this paper (X, τ) , (Y, σ) and (Z, η) represent topological spaces on which no separation axioms are assumed unless otherwise mentioned. For a subset A of space

(X, τ) the $\text{cl}(A)$, $\text{int}(A)$ and A^c denote the closure of A , the interior of A and the complement of A in X respectively.

We recall the following definitions:

Definition 2.01 : A subset A of a topological space (X, τ) is called semi-open¹ (resp. semi-closed, semi pre-open³) if $A \subseteq \text{cl}(\text{int}(A))$ (resp. $\text{int}(\text{cl}(A)) \subseteq A$, $A \subseteq \text{cl}(\text{int}(\text{cl}(A)))$).

Definition 2.02 : A subset A of a topological space (X, τ) is called g -closed² (resp. sg -closed⁴, gs -closed⁵, ψ -closed¹¹, g^* -closed¹²) set if $\text{cl}(A) \subseteq U$ (resp. $\text{scl}(A) \subseteq U$, $\text{scl}(A) \subseteq U$, $\text{scl}(A) \subseteq U$, $\text{cl}(A) \subseteq U$) whenever $A \subseteq U$ and U is open (resp. semi open, open, sg -open, g -open) set in (X, τ) .

Definition 2.03 : A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is called g -closed map¹⁶ (resp. sg -closed map⁸, gs -closed map⁸, ψ -closed map¹⁵, g^* -closed map¹²) if the image of each closed set in (X, τ) is closed set (resp. sg -closed set, gs -closed set, ψ -set, g^* -closed set) in (Y, σ) .

Definition 2.04: A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is called g -continuous⁶ (resp. sg -continuous⁷, gs -continuous¹⁰, ψ -continuous¹¹, g -irresolute⁶, sg -irresolute⁷, gs -irresolute¹⁰, ψ -irresolute¹¹) if the inverse image of every σ -closed (resp. closed, closed, closed, g -closed, sg -closed, gs -closed, ψ -closed) set in Y is g -closed (resp. sg -closed, gs -closed, ψ -closed, g -closed, sg -closed, gs -closed, ψ -closed) set in X .

Definition 2.05 : A bijection $f : (X, \tau) \rightarrow (Y, \sigma)$ is called (i) g -homeomorphism¹⁴ if f is both g -continuous and g -open (ii) sg -homeomorphism¹⁰ if f is both sg -continuous and sg -open (iii) gs -homeomorphism¹⁰ if f is both gs -continuous and gs -open (iv) ψ -homeomorphism¹⁵ if f is both ψ -continuous and ψ -open.

Definition 2.06: Let (X, τ) be a topological space and $A \subseteq X$. Then $\overset{0}{g}$ -closure of A (briefly $\overset{0}{g}\text{-cl}(A)$ ¹²) is defined as the intersection of all $\overset{0}{g}$ -closed sets containing A .

Definition 2.07: Let (X, τ) be a topological space and $A \subseteq X$. Then $\overset{0}{g}$ -interior of A (briefly $\overset{0}{g}\text{-int}(A)$ ¹³) is defined as the union of all $\overset{0}{g}$ -open sets contained in A .

3. $\overset{0}{g}$ -Closed maps :

In this section we introduce the notions of $\overset{0}{g}$ -closed maps, $\overset{0}{g}$ -open maps, $\overset{0}{g}^*$ -closed maps and $\overset{0}{g}^*$ -open maps in topological spaces and obtained certain characterizations of these maps.

Definition 3.01: A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is called $\overset{0}{g}$ -closed (resp. $\overset{0}{g}$ -open) map if $f(A)$ is $\overset{0}{g}$ -closed (resp. $\overset{0}{g}$ -open) set in (Y, σ) for every closed (open) set A of (X, τ) .

Theorem 3.02: (i) Every closed map

and g^* -closed map is $\overset{0}{g}$ -closed map.

(ii) Every closed map and g^* -closed map is $\overset{0}{g}$ -closed map.

Next examples show that the converse of the above theorem is not true in general.

Example 3.03: Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, \{b\}, X\}$ and $\sigma = \{\phi, \{a\}, Y\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping then f is $\overset{0}{g}$ -closed map. However f is not closed map and g^* -closed map.

Example 3.04: Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, \{a, b\}, X\}$ and $\sigma = \{\phi, \{a\}, \{c\}, \{a, c\}, Y\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping then f is g -closed map. However f is not $\overset{0}{g}$ -closed map.

Theorem 3.05: Every $\overset{0}{g}$ -closed map is g -closed map⁹.

Theorem 3.06: A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ -closed map iff $\overset{0}{g}\text{-cl}(f(A)) \subseteq f(\text{cl}(A))$ for every subset A of (X, τ) .

Proof: Suppose that f is $\overset{0}{g}$ -closed map and $A \subseteq X$. Then $f(\text{cl}(A))$ is $\overset{0}{g}$ -closed in (Y, σ) . We have $f(A) \subseteq f(\text{cl}(A))$ and by theorem (4.07) and (4.08) of [13], $\overset{0}{g}\text{-cl}(f(A)) \subseteq \overset{0}{g}\text{-cl}(f(\text{cl}(A))) = f(\text{cl}(A))$.

Conversely let A be any closed set in (X, τ) . Then $A = \text{cl}(A)$ and so $f(A) = f(\text{cl}(A)) \supseteq \overset{0}{g}\text{-cl}(f(A))$, by hypothesis. We have $f(A)$

$\subseteq \overset{0}{g}\text{-cl}(f(A))$ by theorem (4.07) of [13].

Therefore $f(A) = \overset{0}{g}\text{-cl}(f(A))$ i.e. $f(A)$ is $\overset{0}{g}$ -closed by theorem (4.07) of [13] and hence f is $\overset{0}{g}$ -closed map.

Theorem 3.07 : A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ -closed iff for each subset A of (Y, σ) and for each open set B containing $f^{-1}(A)$ there exists a $\overset{0}{g}$ -open set C of (Y, σ) such that $A \subseteq C$ and $f^{-1}(C) \subseteq B$.

Theorem 3.08: If $f : (X, \tau) \rightarrow (Y, \sigma)$ be a closed map and $g : (Y, \sigma) \rightarrow (Z, \eta)$ be a $\overset{0}{g}$ -closed map then their composition $\text{gof} : (X, \tau) \rightarrow (Z, \eta)$ is $\overset{0}{g}$ -closed map.

Remark 3.09: The following example show that the composition of two $\overset{0}{g}$ -closed maps need not be $\overset{0}{g}$ -closed map.

Example 3.10: Let $X = Y = Z = \{a, b, c\}$, $\tau = \{\phi, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$, $\sigma = \{\phi, \{c\}, Y\}$ and $\eta = \{\phi, \{a\}, \{c\}, \{a, c\}, Z\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping and $g : (Y, \sigma) \rightarrow (Z, \eta)$ by identity mapping then f and g both are $\overset{0}{g}$ -closed maps but their composition $\text{gof} : (X, \tau) \rightarrow (Z, \eta)$ is not a $\overset{0}{g}$ -closed map.

Theorem 3.11: If $f : (X, \tau) \rightarrow (Y, \sigma)$ and $g : (Y, \sigma) \rightarrow (Z, \eta)$ be two mappings such that their composition $\text{gof} : (X, \tau) \rightarrow (Z, \eta)$ be a $\overset{0}{g}$ -closed map then the following are true

(i) If f is continuous and surjective, then g is $\overset{0}{g}$ -closed map.

(ii) If g is $\overset{0}{g}$ -irresolute and injective, then f is $\overset{0}{g}$ -closed map.

Theorem 3.12: If $f : (X, \tau) \rightarrow (Y, \sigma)$ be a $\overset{0}{g}$ -closed map and $g : (Y, \sigma) \rightarrow (Z, \eta)$ be a closed map, then their composition $g \circ f : (X, \tau) \rightarrow (Z, \eta)$ need not be a $\overset{0}{g}$ -closed map.

The following example supports the above theorem.

Example 3.13: Let $X = Y = Z = \{a, b, c\}$, $\tau = \{\emptyset, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$, $\sigma = \{\emptyset, \{a\}, \{b, c\}, Y\}$ and $\eta = \{\emptyset, \{b\}, \{c\}, \{b, c\}, Z\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping and $g : (Y, \sigma) \rightarrow (Z, \eta)$ by $g(a) = a = g(b)$, $g(c) = c$. Then f is $\overset{0}{g}$ -closed map and g is closed map but their composition $g \circ f : (X, \tau) \rightarrow (Z, \eta)$ is not a $\overset{0}{g}$ -closed map.

Theorem 3.14: Let f_A be the restriction of a map $f : (X, \tau) \rightarrow (Y, \sigma)$ to a subset A of (X, τ) then

(i) If $f : (X, \tau) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ -closed and A is a closed subset of (X, τ) , then $f_A : (A, \tau_A) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ -closed.

(ii) If $f : (X, \tau) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ -closed (resp. closed) and $A = f^{-1}(B)$ for some closed (resp. $\overset{0}{g}$ -closed) set B of (Y, σ) then $f_A : (A, \tau_A) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ -closed.

Proof: (i) Let B be a closed set of A . Then $B = A \cap C$ for some closed set C of (X, τ) and so B is closed in (X, τ) . By hypothesis, $f(B)$ is $\overset{0}{g}$ -closed in (Y, σ) . But $f(B) = f_A(B)$ and so f_A is a $\overset{0}{g}$ -closed map.

(ii) Let C be a closed set of A . Then $C = A \cap D$ for some closed set D of (X, τ) . Now $f_A(C) = f(C) = f(A \cap D) = f(f^{-1}(B) \cap D) = B \cap f(D)$. Since f is $\overset{0}{g}$ -closed, $f(D)$ is $\overset{0}{g}$ -closed and so $B \cap f(D)$ is $\overset{0}{g}$ -closed in (Y, σ) by theorem (4.09) of [13]. Thus f_A is $\overset{0}{g}$ -closed map.

Theorem 3.15: For any bijective $f : (X, \tau) \rightarrow (Y, \sigma)$ the following statements are equivalent.

- (i) $f^{-1} : (Y, \sigma) \rightarrow (X, \tau)$ is $\overset{0}{g}$ -continuous.
- (ii) f is $\overset{0}{g}$ -open map and
- (iii) f is $\overset{0}{g}$ -closed map.

Definition 3.16: Let x be a point of (X, τ) and A be a subset of X . Then A is called a $\overset{0}{g}$ -neighborhood (briefly $\overset{0}{g}$ -nbd) of x in (X, τ) if there exists a $\overset{0}{g}$ -open set B of (X, τ) such that $x \in B \subseteq A$.

Theorem 3.17: Let $f : (X, \tau) \rightarrow (Y, \sigma)$ be a map then the following statements are equivalent.

- (i) f is $\overset{0}{g}$ -open map.
- (ii) For a subset A of (X, τ) , $f(\text{int}(A)) \subseteq \overset{0}{g}\text{-int}(f(A))$.
- (iii) For each $x \in X$ and for each nbd A of

x in (X, τ) , there exists a $\overset{0}{g}$ -nbd of $f(x)$ in (Y, σ) such that $B \subseteq f(A)$. σ

Proof: (i) $\Rightarrow$ (ii) Suppose f is $\overset{0}{g}$ -open.

Let $A \subseteq X$. Since $\text{int}(A)$ is open in (X, τ) , $f(\text{int}(A))$ is $\overset{0}{g}$ -open in (Y, σ) . Hence $\text{int}(A) \subseteq f(A)$ and we have, $f(\text{int}(A)) \subseteq \overset{0}{g}\text{-int}f(A)$.

(ii) $\Rightarrow$ (iii) Suppose (ii) holds. Let $x \in X$ and A be an arbitrary nbd. of x in (X, τ) . Then there exists an open set G such that $x \in G \subseteq A$. By assumption, $f(G) \subseteq f(\text{int}(G)) \subseteq \text{int}f(G)$. This implies $f(G) = \overset{0}{g}\text{-int}f(G)$. Therefore, $f(G)$ is $\overset{0}{g}$ -open in (Y, σ) . Further, $f(x) \in f(G) \subseteq f(A)$ and so (iii) holds, by taking $B = f(G)$.

(iii) $\Rightarrow$ (i) Let A be an open set in (X, τ) , $x \in A$ and $f(x) = y$. Then for each $x \in A$, $y \in f(A)$, by assumption there exists a -nbd U_y of y in (Y, σ) such that $U_y \subseteq f(A)$. Since U_y is a $\overset{0}{g}$ -nbd of y , there exists a $\overset{0}{g}$ -open set V_y in (Y, σ) such that $y \in V_y \subseteq U_y$. Therefore $f(A) = \cup\{V_y : y \in f(A)\}$. Since any union of $\overset{0}{g}$ -open sets is $\overset{0}{g}$ -open set¹³, $f(A)$ is a $\overset{0}{g}$ -open set of (Y, σ) . Thus, f is $\overset{0}{g}$ -open mapping.

Theorem 3.18 : A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ -open if and only if for any subset B of (Y, σ) and for any closed set C containing $f^{-1}(B)$, there exists a $\overset{0}{g}$ -closed set A of (Y, σ) containing B such that $f^{-1}(A) \subseteq C$.

Corollary 3.19: A function $f : (X, \tau)$

$\rightarrow (Y, \sigma)$ is $\overset{0}{g}$ -open mapping if and only if $f^{-1}(\overset{0}{g}\text{-cl}(B)) \subseteq \text{cl}(f^{-1}(B))$ for every subset B of (Y, σ) .

Definition 3.20: A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be a $\overset{0}{g}$ *-closed (resp. $\overset{0}{g}$ *-open) map if the image $f(A)$ is $\overset{0}{g}$ -closed (resp. $\overset{0}{g}$ -open) set in (Y, σ) for every $\overset{0}{g}$ -closed (resp. $\overset{0}{g}$ -open) set A in (X, τ) .

Theorem 3.21: Every $\overset{0}{g}$ *-closed map is $\overset{0}{g}$ -closed map.

The converse is not true in general as seen from the following example.

Example 3.22: Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{b, c\}, X\}$ and $\sigma = \{\phi, \{c\}, Y\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping then f is $\overset{0}{g}$ -closed map but not $\overset{0}{g}$ *-closed map.

Theorem 3.23: A map $f : (X, \tau) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ *-closed iff $\overset{0}{g}\text{-cl}(f(A)) \subseteq f(\overset{0}{g}\text{-cl}(A))$ for every subset A of (X, τ) .

Proof: Similar to theorem (3.06).

Theorem 3.24: For any bijection $f : (X, \tau) \rightarrow (Y, \sigma)$ the following are equivalent

- (i) $f^{-1} : (Y, \sigma) \rightarrow (X, \tau)$ is $\overset{0}{g}$ -irresolute.
- (ii) f is a $\overset{0}{g}$ *-open map.
- (iii) f is a $\overset{0}{g}$ *-closed map.

Proof: Similar to theorem (3.15).

4. $\overset{0}{g}$ -Homeomorphisms :

In this section we introduce the following definitions.

Definition 4.01: A bijection $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be $\overset{0}{g}$ -homeomorphisms if f is $\overset{0}{g}$ -continuous and $\overset{0}{g}$ -open maps i.e. both f and f^{-1} are $\overset{0}{g}$ -continuous maps.

Theorem 4.02: Every homeomorphism is $\overset{0}{g}$ -homeomorphism.

The converse of the above theorem is not true in general as it can be seen from the following example.

Example 4.03: Let $X = Y = \{a, b, c\}$, $\tau = \{\emptyset, X\}$ and $\sigma = \{\emptyset, \{a\}, Y\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping then f is $\overset{0}{g}$ -homeomorphism but not homeomorphism.

Theorem 4.04: Every $\overset{0}{g}$ -homeomorphism is gs -homeomorphism.

The converse of the above theorem is not true in general as it can be seen from the following example.

Example 4.05: Let $X = Y = \{a, b, c\}$, $\tau = \{\emptyset, \{b\}, \{a, c\}, X\}$ and $\sigma = \{\emptyset, \{a\}, \{a, b\}, Y\}$.

Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping then f is gs -homeomorphism but not $\overset{0}{g}$ -homeomorphism.

Theorem 4.06: Every $\overset{0}{g}$ -homeomorphism is g -homeomorphism.

Definition 4.07: A bijection $f : (X, \tau) \rightarrow (Y, \sigma)$ is said to be $\overset{0}{g}^*$ -homeomorphism if both f and f^{-1} are $\overset{0}{g}$ -irresolute.

We denote the family of all $\overset{0}{g}^*$ -homeomorphism of a topological space (X, τ) onto itself by $\overset{0}{g}^*h(X, \tau)$.

Theorem 4.08: Every $\overset{0}{g}^*$ -homeomorphism is $\overset{0}{g}$ -homeomorphism.

The converse of the above theorem is not true in general as it can be seen from the following example.

Example 4.09: Let $X = Y = \{a, b, c\}$, $\tau = \{\emptyset, X\}$ and $\sigma = \{\emptyset, \{a, b\}, Y\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping then f is $\overset{0}{g}$ -homeomorphism but not $\overset{0}{g}^*$ -homeomorphism.

Therefore the class of $\overset{0}{g}$ -homeomorphism properly contain the class of homeomorphism and properly contained in the class of g -homeomorphism, the class of gs -homeomorphism

Remark 4.10: The following examples show that $\overset{0}{g}$ -homeomorphism is independent from sg -homeomorphism and Ψ -homeomorphism.

Example 4.11: Let $X = Y = \{a, b, c\}$, $\tau = \{\emptyset, \{a\}, X\}$ and $\sigma = \{\emptyset, \{c\}, Y\}$. Define f :

$(X, \tau) \rightarrow (Y, \sigma)$ by identity mapping then f is $\overset{0}{g}$ -homeomorphism but not sg-homeomorphism and Ψ -homeomorphism

$c\}, Y\}$. Define $f : (X, \tau) \rightarrow (Y, \sigma)$ by identity mapping then f is sg-homeomorphism and Ψ -homeomorphism but not $\overset{0}{g}$ -homeomorphism

Example 4.12: Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, \{a\}, \{a, b\}, X\}$ and $\sigma = \{\phi, \{b\}, \{b, c\}, Y\}$.

All the above discussion can be summarized by the following diagram: ----

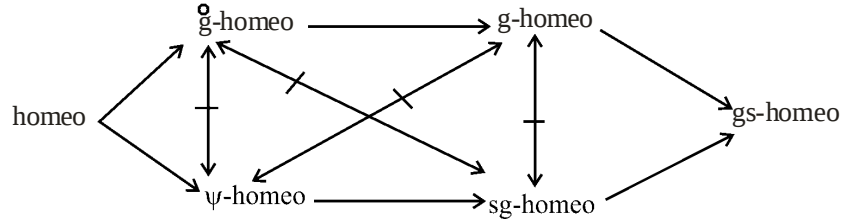


Diagram (4.13)

Theorem 4.14: If $f : (X, \tau) \rightarrow (Y, \sigma)$ and $g : (Y, \sigma) \rightarrow (Z, \eta)$ are $\overset{0}{g}$ *-homeomorphism, then their composition $g \circ f : (X, \tau) \rightarrow (Z, \eta)$ is also $\overset{0}{g}$ *-homeomorphism.

Theorem 4.15: If $f : (X, \tau) \rightarrow (Y, \sigma)$ be a bijective and $\overset{0}{g}$ -continuous map then following statements are equivalent.

- (i) f is $\overset{0}{g}$ -open map.
- (ii) f is $\overset{0}{g}$ -homeomorphism.
- (iii) f is $\overset{0}{g}$ -closed map.

Theorem 4.16: The set $\overset{0}{g}$ *-h(X, τ) is a group under the composition of maps.

Proof: Define a binary operation $\Theta : \overset{0}{g}$ *-h(X, τ) $\times$ $\overset{0}{g}$ *-h(X, τ) $\rightarrow$ $\overset{0}{g}$ *-h(X, τ) by $f \Theta g = g \circ f$ for all f and $g \in \overset{0}{g}$ *-h(X, τ) and $\circ$ is the usual operation of composition of maps. Then by theorem (4.14) $g \Theta f \in \overset{0}{g}$ *-h(X, τ).

Again composition of maps is associative and the identity map $I : (X, \tau) \rightarrow (X, \tau)$ belonging to $\overset{0}{g}$ *-h(X, τ) serves as the identity element of $\overset{0}{g}$ *-h(X, τ). If $f \in \overset{0}{g}$ *-h(X, τ), then $f^{-1} \in \overset{0}{g}$ *-h(X, τ) such that $f \Theta f^{-1} = f^{-1} \Theta f = I$ and so inverse exists for each element of $\overset{0}{g}$ *-h(X, τ). Thus $(\overset{0}{g}$ *-h(X, τ), Θ) is a group under the operation of composition of maps.

Theorem 4.17: If $f : (X, \tau) \rightarrow (Y, \sigma)$ be a $\overset{0}{g}$ *-homeomorphism, then f induces an isomorphism from the group $\overset{0}{g}$ *-h(X, τ) onto the group $\overset{0}{g}$ *-h(Y, σ).

Proof: Define $\psi_f : \overset{0}{g}$ *-h(X, τ) $\rightarrow$ $\overset{0}{g}$ *-h(Y, σ) by $\psi_f(h) = f \circ h \circ f^{-1}$ for every $h \in \overset{0}{g}$ *-h(X, τ). Then ψ_f is a bijection. Further, for all $h_1, h_2 \in \overset{0}{g}$ *-h(X, τ), $\psi_f(h_1 \circ h_2) = f \circ (h_1 \circ h_2) \circ f^{-1} = (f \circ h_1 \circ f^{-1}) \circ (f \circ h_2 \circ f^{-1}) = \psi_f(h_1) \circ \psi_f(h_2)$ so ψ_f

is a homeomorphism and so it is an isomorphism induced by f .

Theorem 4.18: $\overset{0}{g}$ *-homeomorphism is an equivalence relation in the collection of all topological spaces.

Proof: Follows from theorem (4.14).

Theorem 4.19: If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a $\overset{0}{g}$ *-homeomorphism, then $\overset{0}{g}\text{-cl}(f^{-1}(A)) \subseteq f^{-1}(\overset{0}{g}\text{-cl}(A))$ for all $A \subseteq Y$.

Theorem 4.20: If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a $\overset{0}{g}$ *-homeomorphism, then $\overset{0}{g}\text{-cl}(f(A)) = f(\overset{0}{g}\text{-cl}(A))$ for all $A \subseteq X$.

Proof: Follows from theorem (4.19).

Theorem 4.21: If $f : (X, \tau) \rightarrow (Y, \sigma)$ is $\overset{0}{g}$ *-homeomorphism, then $f(\overset{0}{g}\text{-int}(A)) = \overset{0}{g}\text{-int}(f(A))$ for all $A \subseteq X$.

Proof: Follows from theorem (4.20).

Theorem 4.22: If $f : (X, \tau) \rightarrow (Y, \sigma)$ is a $\overset{0}{g}$ *-homeomorphism, then $f^{-1}(\text{-int}(A)) = \overset{0}{g}\text{-int}(f^{-1}(A))$ for all $A \subseteq Y$.

Proof: Follows from theorem (4.21).

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