

A New Type of Closed Sets in Bitopological Spaces

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Abstract

In this paper, we introduce $\bar{g}$ -closed sets¹⁹ in bitopological spaces. Properties of these sets are investigated and we introduce the two new bitopological spaces $(i, j)\text{-}\bar{T}$ and $(i, j)\text{-}\bar{T}^*$ spaces as applications. Further we introduce and study $\bar{g}$ -continuity¹⁹ in bitopological spaces.

Key words : $(i, j)\text{-}\bar{g}$ -closed sets; $(i, j)\text{-}\bar{T}$ spaces; $(i, j)\text{-}\bar{T}^*$ spaces;
 $\bar{D}$ (i, j) -continuity.

1. Introduction

A triple (X, τ_1, τ_2) where X is non empty set and τ_1, τ_2 are two topologies on X is called a bitopological space. Kelly³ in 1985 initiated and study of such space. Fukutaka⁶ in 1985 introduced the concept of g -closed sets² in bitopological spaces and after that many authors turned their attention towards generalizations of various concepts of topology by considering bitopological spaces. Recently Shailendra and Manoj¹⁹ introduced and studied the concepts of $\bar{g}$ -closed sets and $\bar{g}$ -continuity in topological spaces. $\bar{g}$ -closed sets lies between closed sets and g -closed sets.

In this paper we introduce the concepts of $\bar{g}$ -closed sets¹⁹, $\bar{T}$ -spaces¹⁹, $\bar{T}^*$ -spaces¹⁹

and $\bar{g}$ -continuity¹⁹ for bitopological spaces and investigate some of their properties.

2. Preliminaries:

If A is a subset of X with a topologt τ , then the closure of A is denoted by $\tau\text{-cl}(A)$ or $\text{cl}(A)$, the interior of A is denoted by $\tau\text{-int}(A)$ or $\text{int}(A)$ and the complement of A is denoted by A^c .

We recall the following definitions:

Definition 2.01 : (i) A subset A of a topological space (X, τ) is called semi-open¹. (resp. regular open⁴, pre-open²) if $A \subseteq \text{cl}(\text{int}(A))$ (resp. $A = \text{int}(\text{Cl}(A))$, $A \subseteq \text{int}(\text{cl}(A))$).

(ii) A subset A of a topological space (X, τ) is called g -closed set². (resp. $\hat{g}$ -closed set¹⁴, $\hat{g}$ -closed set¹⁷, $\bar{g}$ -closed set¹⁹) if $\text{cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is open (resp. semi-open, sg -open, $\hat{g}$ -open) in (X, τ) .

Definition 2.02 : The intersection of all pre-closed sets containing A is called the pre-closure of A and it is denoted by $\text{pcl}(A)$.

Throughout this paper, X and Y represent non-empty bitopological spaces (X, τ_1, τ_2) and (Y, σ_1, σ_2) on which no separation axioms are assumed unless otherwise explicitly mentioned and integers $i, j, k \in \{1, 2\}$. For a subset A of X , $\tau_i\text{-cl}(A)$ (resp. $\tau_i\text{-int}(A)$) denote the closure (resp. interior) of A w.r.t. topology τ_i . We denote the family of all $\hat{g}$ -open subsets

of X w.r.t. topology τ_i by $\hat{G} O(X, \tau_i)$ and the family of all τ_j -closed sets is denoted by F_j . By (i, j) we mean the pair of topologies (τ_i, τ_j) .

Definition 2.03 : A subset A of a bitopological space (X, τ_1, τ_2) is called :

- (i) (i, j) - g -closed⁶ if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and $U \in \tau_i$.
- (ii) (i, j) - rg -closed⁸ if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is regular open in τ_i .
- (iii) (i, j) - gpr -closed¹² if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is regular open in τ_i .
- (iv) (i, j) - Wg -closed¹⁰ if $\tau_j\text{-cl}(\tau_i\text{-int}(A)) \subseteq U$ whenever $A \subseteq U$ and $U \in \tau_i$.
- (v) (i, j) - ω -closed¹² if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is semi-open in τ_i .

- (vi) (i, j) - g^* -closed¹⁵ if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is generalized-open in τ_i .
- (vii) (i, j) - $*g$ -closed¹⁸ if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and U is $\hat{g}$ -open in τ_i .

The family of all (i, j) - g -closed (resp. (i, j) - rg -closed, (i, j) - gpr -closed, (i, j) - Wg -closed, (i, j) - ω -closed, (i, j) - g^* -closed and (i, j) - $*g$ -closed) subsets of a bitopological space (X, τ_1, τ_2) is denoted by $D(i, j)$ (resp. $\text{Dr}(i, j)$, $\zeta(i, j)$, $W(i, j)$, $C(i, j)$, $D^*(i, j)$ and $*D(i, j)$).

Definition 2.04 : (i) A bitopological space (X, τ_1, τ_2) is said to be (i, j) - $T_{1/2}$ ⁶ (resp. (i, j) - $T^*_{1/2}$ ¹⁵, (i, j) - $*T_{1/2}$ ¹⁵, (i, j) - $gT^*_{1/2}$ ¹⁸ and (i, j) - $*g^*T_{1/2}$ ¹⁸) if every (i, j) - g -closed (resp. (i, j) - g^* -closed, (i, j) - g -closed, (i, j) - $*g$ -closed, (i, j) - g -closed) sets is τ_j -closed (resp. τ_j -closed, (i, j) - g^* -closed, τ_j -closed, (i, j) - $*g$ -closed).

(ii) A bitopological space (X, τ_1, τ_2) is said to be strongly pairwise- $T_{1/2}$ ⁶ (resp. strongly pairwise $T^*_{1/2}$ ¹⁵, strongly pairwise $*gT^*_{1/2}$ ¹⁸) space if it is $(1, 2)$ - $T_{1/2}$ and $(2, 1)$ - $T_{1/2}$ (resp. $(1, 2)$ - $T^*_{1/2}$ and $(2, 1)$ - $T^*_{1/2}$, $(1, 2)$ - $gT^*_{1/2}$ and $(2, 1)$ - $*gT^*_{1/2}$) space.

Definition 2.05 : A map $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is called :

- (i) τ_j - σ_k -continuous⁷ if $f^{-1}(U) \in \tau_j$ for every $U \in \sigma_k$.
- (ii) $D(i, j)$ - σ_k -continuous⁷ (resp. $\text{Dr}(i, j)$ - σ_k -continuous⁸, $\zeta(i, j)$ - σ_k -continuous¹², $W(i, j)$ - σ_k -continuous¹⁰, $C(i, j)$ - σ_k -continuous¹², $D^*(i, j)$ - σ_k -continuous¹⁵ and $*D(i, j)$ - σ_k -continuous¹⁸) if the inverse image of every σ_k -closed set is

(i, j)-g-closed (resp. (i, j)-rg-closed, (i, j)-gpr-closed, (i, j)-Wg-closed, (i, j)- ω -closed (i, j)- g^* -closed and (i, j)- *g -closed) set in (X, τ_1, τ_2) .

Definiiton 2.06 : A topological space (X, τ) is called $\overline{T}$ -space¹⁹ if every $\overline{g}$ -closed set is closed.

3. (i, j)- $\overline{g}$ -Closed sets:

In this section we introduce the concepts of $\overline{g}$ -closed sets in bitopological spaces.

Definition 3.01 : A subset A of a bitopological space (X, τ_1, τ_2) is said to be an (i,j)- $\overline{g}$ -closed set if $\tau_j\text{-cl}(A) \subseteq U$ whenever $A \subseteq U$ and $U \in \hat{G}O(X, \tau_i)$.

Family of all (i, j)- $\overline{g}$ -closed sets in (X, τ_1, τ_2) is denoted by $\overline{D}(i, j)$.

Remark 3.02 : By setting $\tau_1 = \tau_2$ in definition (3.01), (i, j)- $\overline{g}$ -closed set is $\overline{g}$ -closed set.

Proposition 3.03 : If A is τ_j -closed subset of (X, τ_1, τ_2) , then A is (i, j)- $\overline{g}$ -closed.

The converse of the above proposition is not necessarily true as seen from following example.

Example 3.04 : Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$ and $\tau_2 = \{\phi, \{c\},$

$\{a, c\}, X\}$ then the subset $\{a, c\}$ is (1, 2)- $\overline{g}$ -closed but not τ_2 -closed.

Proposition 3.05 : In a bitopological space every (i, j)- $\overline{g}$ -closed set is (i, j)-g-closed but not conversely.

Proposition 3.06 : In a bitopological space every (i, j)- $\overline{g}$ -closed set is (i) (i, j)-rg-closed (ii) (i, j)-gpr-closed (iii) (i, j)-Wg-closed.

The following examples show that the reverse implications of the above proposition are not true.

Example 3.07 : Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{c\}, \{a, c\}, X\}$ and $\tau_2 = \{\phi, \{a\}, X\}$ then the subset $\{a, c\}$ is (1, 2)-rg-closed but not (1, 2)- $\overline{g}$ -closed.

Example 3.08 : Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$ and $\tau_2 = \{\phi, \{a, b\}, X\}$ then the subset $\{a\}$ is (1, 2)-gpr-closed but not (1, 2)- $\overline{g}$ -closed.

Example 3.09 : In example (3.08) $\{b, c\}$ is (1, 2)-Wg-closed but not (1, 2)- $\overline{g}$ -closed.

Remark 3.10 : The following example shows that (i, j)- $\overline{g}$ -closed set is not (i, j)- ω -closed set.

Example 3.11 : Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$ and $\tau_2 = \{\phi, \{a\}, \{b, c\}, X\}$ then the subset $\{a, c\}$ is (1, 2)- $\overline{g}$ -closed but not (1, 2)- ω -closed.

Remark 3.12 : It can be shown that

Proposition 3.21 : If $A, B \in \overline{D}(i, j)$, then $A \cup B \in \overline{D}(i, j)$.

Remark 3.22 : The following example shows that the intersection of two (i, j) - $\overline{g}$ -closed sets need not be (i, j) - $\overline{g}$ -closed set.

Example 3.23 : In example (3.14), $\{a, b\}$ and $\{a, c\}$ are $(1, 2)$ - $\overline{g}$ -closed sets but their intersection $\{a\}$ is not a $(1, 2)$ - $\overline{g}$ -closed set.

Remark 3.24 : $(1, 2)$ is necessarily not equal to $(2, 1)$, For in example (3.14), $(1, 2) \neq (2, 1)$.

Proposition 3.25 : If $\tau_1 \subseteq \tau_2$ in (X, τ_1, τ_2) then $\overline{D}(2, 1) \subseteq \overline{D}(1, 2)$.

The following example shows that the reverse implication of the above proposition is not true.

Example 3.26 : Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{b\}, X\}$ and $\tau_2 = \{\phi, \{b, c\}, X\}$ then $\overline{D}(2, 1) \subseteq \overline{D}(1, 2)$ but τ_1 is not contain in τ_2 .

Proposition 3.27 : For each element x of (X, τ_1, τ_2) , $\{x\}$ is τ_i - $\hat{\overline{g}}$ -closed or $\{x\}^c$ is (i, j) - $\overline{g}$ -closed.

Propositon 3.28 : If A is (i, j) - $\overline{g}$ -closed then $\tau_j\text{-cl}(A) - A$ contains no non-empty τ_i - $\hat{\overline{g}}$ -closed set.

Proof : Let A be an (i, j) - $\overline{g}$ -closed

set and B be τ_i - $\hat{\overline{g}}$ -closed set such that $B \subseteq \tau_j\text{-cl}(A) = A$. Since $A \in \overline{D}(i, j)$, we have $\tau_j\text{-cl}(A) \subseteq B^c$. Thus $B \subseteq \tau_j\text{-cl}(A) \cap (\tau_j\text{-cl}(A))^c = \phi$.

The converse of the above proposition is not true as it can be seen from the following example.

Example 3.29 : Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b, c\}, X\}$ and $\tau_2 = \{\phi, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$. If $A = \{b\}$ then $\tau_1\text{-cl}(A) = A = \{c\}$ does not contain any non-empty τ_2 - $\hat{\overline{g}}$ -closed set. But A is not a $(2, 1)$ - $\overline{g}$ -closed.

Proposition 3.30 : If A is (i, j) - $\overline{g}$ -closed set in (X, τ_1, τ_2) then A is τ_j -closed iff $\tau_j\text{-cl}(A) = A$ is τ_i - $\hat{\overline{g}}$ -closed.

Proposition 3.31 : If A is an (i, j) - $\overline{g}$ -closed set of (X, τ_1, τ_2) such that $A \subseteq B \subseteq \tau_j\text{-cl}(A)$ then B is also an (i, j) - $\overline{g}$ -closed set of (X, τ_1, τ_2) .

Proposition 3.32 : Let $A \subseteq Y \subseteq X$ and A is (i, j) - $\overline{g}$ -closed in X . Then A is (i, j) - $\overline{g}$ -closed related to Y .

Theorem 3.33 : In a bitopological space (X, τ_1, τ_2) , $\hat{\overline{G}} O(X, \tau_i) \subseteq F_j$ (Family of all closed sets in τ_j) iff every subset of X is an (i, j) - $\overline{g}$ -closed set.

Proof : Suppose that $\hat{\overline{G}} O(X, \tau_i) \subseteq$

F_j . Let A be a subset of X such that $A \subseteq U$ where $U \in (X, \tau_i)$ then $\tau_j\text{-cl}(A) \subseteq \tau_j\text{-cl}(U) = U$ and hence A is $(i, j)\text{-}\bar{g}$ -closed.

Conversely let every subset of X is $(i, j)\text{-}\bar{g}$ -closed. Let $U \in \hat{G} O(X, \tau_i)$. Since U is $(i, j)\text{-}\bar{g}$ -closed, we have $\tau_j\text{-cl}(U) \subseteq U$. So $U \in F_j$ and hence $\hat{G} O(X, \tau_i) \subseteq F_j$.

4. (i, j) -spaces and (i, j) -*spaces

In this section we introduce the following definitions:

Definition 4.01 : A bitopological space (X, τ_1, τ_2) is said to be an $(i, j)\text{-}\bar{T}$ space if every $(i, j)\text{-}\bar{g}$ -closed set is τ_j -closed.

Definition 4.02 : A bitopological space (X, τ_1, τ_2) is said to be an $(i, j)\text{-}\bar{T}^*$ space if every $(i, j)\text{-g}$ -closed set is $(i, j)\text{-}\bar{g}$ -closed set.

Proposition 4.03 : If (X, τ_1, τ_2) is $(i, j)\text{-}T_{1/2}$ space then it is $(i, j)\text{-}\bar{T}$ space but converse is not necessarily true.

Proposition 4.04 : If (X, τ_1, τ_2) is $(i, j)\text{-}\bar{T}$ space then it is $(i, j)\text{-}^*gT_{1/2}^*$ space but not conversely.

Example 4.05 : Let $X = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{a\}, X\}$ and $\tau_2 = \{\emptyset, \{b\}, \{a, c\}, X\}$. Then (X, τ_1, τ_2) is $(2, 1)\text{-}^*gT_{1/2}^*$ space but not $(2, 1)\text{-}\bar{T}$ space.

Theorem 4.06 : A bitopological space

(X, τ_1, τ_2) is an $(i, j)\text{-}\bar{T}$ space iff $\{x\}$ is τ_j -open or $\tau_i\text{-}\hat{g}$ -closed for each $x \in X$.

Proof : Suppose that $\{x\}$ is not $\tau_i\text{-}\hat{g}$ -closed then $\{x\}^c$ is $(i, j)\text{-}\bar{g}$ -closed by proposition (3.27). Since (X, τ_1, τ_2) is an $(i, j)\text{-}\bar{T}$ space, $\{x\}^c$ is τ_j -closed i.e. $\{x\}$ is τ_j -open.

Conversely let F be an $(i, j)\text{-}\bar{g}$ -closed set, By assumption $\{x\}$ is τ_j -open or $\tau_i\text{-}\hat{g}$ -closed for any $x \in \tau_j\text{-cl}(F)$. Now consider two cases.

Case-I : Suppose $\{x\}$ is τ_j -open. Since $\{x\} \cap F \neq \emptyset$ we have $x \in F$.

Case-II : Suppose $\{x\}$ is $\tau_i\text{-}\hat{g}$ -closed. If $x \notin F$ then $\{x\} \subseteq \tau_j\text{-cl}(F) - F$, which is a contradiction to proposition (3.30) so $x \in F$.

Thus in both cases we conclude that F is τ_j -closed. Hence (X, τ_1, τ_2) is $(i, j)\text{-}\bar{T}$ space.

Remark 4.07 : (X, τ_1, τ_2) is not generally $(1, 2)\text{-}\bar{T}$ space even if both (X, τ_1) and (X, τ_2) are $\bar{T}$ -spaces. It can be shown by the following example.

Example 4.08 : Let $X = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{a\}, \{c\}, \{a, c\}, X\}$ and $\tau_2 = \{\emptyset, \{a\}, \{b\}, \{a, b\}, X\}$. Then (X, τ_1) and (X, τ_2) are $\bar{T}$ -space but (X, τ_1, τ_2) is not $(1, 2)\text{-}\bar{T}$ space.

Definition 4.09 : A bitopological

space (X, τ_1, τ_2) is said to be strongly pairwise $\bar{T}$ -space if it is both $(1, 2)$ - $\bar{T}$ space and $(2, 1)$ - $\bar{T}$ space.

Proposition 4.10 : If (X, τ_1, τ_2) is strongly pairwise $T_{1/2}$ -space then it is strongly pairwise $\bar{T}$ -space.

Proposition 4.11 : If (X, τ_1, τ_2) is strongly pairwise $\bar{T}$ -space then it is strongly pairwise $*gT_{1/2}$ -space.

Proposition 4.12 : Every (i, j) - $\bar{T}$ space is (i, j) - $T_{1/2}$ space but not conversely.

Example 4.13 : In example (4.05), (X, τ_1, τ_2) is $(1, 2)$ - $T_{1/2}$ space but not $(1, 2)$ - $\bar{T}$ space.

Proposition 4.14 : Every (i, j) - $T_{1/2}$ space is (i, j) - $\bar{T}$ space but not conversely.

Example 4.15 : Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, X\}$ and $\tau_2 = \{\phi, \{a\}, \{c\}, \{a, c\}, X\}$. Then (X, τ_1, τ_2) is $(2, 1)$ - $\bar{T}$ space but not $(2, 1)$ - $T_{1/2}$ space.

Proposition 4.16 : Every (i, j) - $*T_{1/2}$ space is (i, j) - $\bar{T}$ space but not conversely.

Example 4.17 : In example (3.11),

(X, τ_1, τ_2) is $(2, 1)$ - $\bar{T}$ space but not $(2, 1)$ - $*T_{1/2}$ space.

Proposition 4.18 : Every (i, j) - $*gT_{1/2}$ space is (i, j) - $\bar{T}$ space but not conversely.

Example 4.19 : In example (3.11), (X, τ_1, τ_2) is $(2, 1)$ - $\bar{T}$ space but not $(2, 1)$ - $*gT_{1/2}$ space.

Remark 4.20 : (i, j) - $\bar{T}$ space is not necessarily (i, j) - $\bar{T}$ space as it can be seen from the following example.

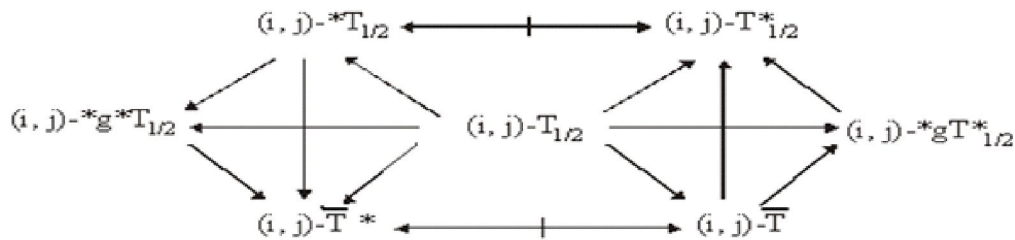
Example 4.21 : In example (3.08), (X, τ_1, τ_2) is $(1, 2)$ - $\bar{T}$ space but not $(1, 2)$ - $\bar{T}$ space.

Remark 4.22 : In a bitopological space (X, τ_1, τ_2) , (i, j) - $\bar{T}$ space is not necessarily (i, j) - $\bar{T}$ space.

Theorem 4.23 : A bitopological space (X, τ_1, τ_2) is an (i, j) - $T_{1/2}$ space iff it is both (i, j) - $\bar{T}$ space and (i, j) - $\bar{T}$ space.

Propositioin 4.24 : If (X, τ_1, τ_2) strongly pairwise $\bar{T}$ -space then it is strongly pairwise $T_{1/2}$ -space.

The following diagram summarizes the above discussions.



5. $\bar{g}$ -Continuous maps and $\bar{g}$ -irresolute maps :

In this section we introduce the following definitions.

Definition 5.01 : A map. $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is called (i, j) - $\bar{g}$ - σ_k -continuous if the inverse image of every σ_k -closed set is an (i, j) - $\bar{g}$ -closed set. It is denoted by $\bar{D}(i, j)$ - σ_k -continuous.

Proposition 5.02 : If $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is τ_j - σ_k -continuous then it is $\bar{D}(i, j)$ - σ_k -continuous but not conversely.

Example 5.03 : Let $X = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, X\}$, $\tau_2 = (\phi, \{b\}, \{a, c\}, X)$ and $Y = \{p, q\}$, $\sigma_1 = \{\phi, \{p\}, Y\}$, $\sigma_2 = \{\phi, \{q\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by $f(c) = p$, $f(a) = q$, $f(b) = q$ then f is $\bar{D}(1, 2)$ - σ_2 -continuous but not τ_2 - σ_2 -continuous.

Proposition 5.04 : Every $\bar{D}(i, j)$ - σ_k -continuous map is $D(i, j)$ - σ_k -continuous map.

Proposition 5.05 : If $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $\bar{D}(i, j)$ - σ_k -continuous then it is (i) $Dr(i, j)$ - σ_k -continuous (ii) $\zeta(i, j)$ - σ_k -continuous (iii) $W(i, j)$ - σ_k -continuous.

However the reverse implications of the above proposition are not true in general as seen from the following examples.

Example 5.06 : Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{a, c\}, X\}$, $\tau_2 = (\phi, \{a, b\}, X)$

and $\sigma_1 = \{\phi, \{b\}, \{a, b\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, \{a, b\}, \{a, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by $f(a) = b$, $f(b) = c$, $f(c) = a$ then f is $Dr(2, 1)$ - σ_2 -continuous but not $\bar{D}(2, 1)$ - σ_2 -continuous.

Example 5.07 : Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$, $\tau_2 = (\phi, \{a, b\}, X)$ and $\sigma_1 = \{\phi, \{a\}, \{b\}, \{a, b\}, Y\}$, $\sigma_2 = \{\phi, \{b\}, \{c\}, \{b, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by $f(a) = c$, $f(b) = a$, $f(c) = b$ then f is $\zeta(1, 2)$ - σ_1 -continuous but not $\bar{D}(1, 2)$ - σ_1 -continuous.

Example 5.08 : Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{b\}, \{c\}, \{b, c\}, \{a, c\}, X\}$, $\tau_2 = (\phi, \{a, b\}, X)$ and $\sigma_1 = \{\phi, \{a\}, \{c\}, \{a, c\}, Y\}$, $\sigma_2 = \{\phi, \{c\}, \{b, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $W(1, 2)$ - σ_2 -continuous but not $\bar{D}(1, 2)$ - σ_2 -continuous.

Proposition 5.09 : If $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $D^*(i, j)$ - σ_k -continuous then it is $\bar{D}(i, j)$ - σ_k -continuous.

However the reverse implication of the above proposition is not true in general as seen from the following example.

Example 5.10 : Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{c\}, \{a, c\}, X\}$, $\tau_2 = (\phi, \{a\}, X)$ and $\sigma_1 = \{\phi, \{a\}, \{a, b\}, \{a, c\}, Y\}$, $\sigma_2 = \{\phi, \{a\}, \{a, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by $f(a) = a$, $f(b) = c$, $f(c) = b$ then f is $\bar{D}(2, 1)$ - σ_1 -continuous but not $D^*(2, 1)$ - σ_1 -continuous.

Proposition 5.11 : If $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $*D(i, j)$ - σ_k -continuous then it is $\bar{D}(i, j)$ - σ_k -continuous.

However the reverse implication of the above proposition is not true in general as seen from the following example.

Example 5.12 : Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{a\}, \{b\}, \{a, b\}, X\}$, $\tau_2 = \{\emptyset, \{a\}, \{b, c\}, X\}$ and $\sigma_1 = \{\emptyset, \{b\}, \{b, c\}, Y\}$, $\sigma_2 = \{\emptyset, \{a\}, \{a, b\}, \{a, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $\overline{D}(2, 1)$ - σ_2 -continuous but not $*D(2, 1)$ - σ_2 -continuous.

Remark 5.13 : $\overline{D}(i, j)$ - σ_k -continuity is not necessarily $C(i, j)$ - σ_k -continuity as seen from the following example.

Example 5.14 : Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\emptyset, \{a\}, \{b, c\}, X\}$, $\tau_2 = \{\emptyset, \{a\}, \{a, b\}, X\}$ and $\sigma_1 = \{\emptyset, \{b\}, \{c\}, \{b, c\}, Y\}$, $\sigma_2 = \{\emptyset, \{b\}, \{a, b\}, \{b, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by $f(a) = c$, $f(b) = b$, $f(c) = a$ then f is $\overline{D}(2, 1)$ - σ_2 -continuous but not $C(2, 1)$ - σ_2 -continuous.

Remark 5.15 : $C(i, j)$ - σ_k -continuity is not necessarily $\overline{D}(i, j)$ - σ_k -continuity.

The following diagram summarizes the above discussions.

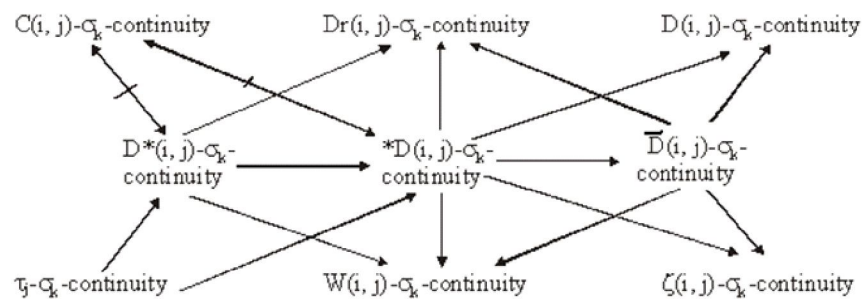


Diagram (5.16)

Theorem 5.17 : Let $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ be a map:

(i) if (X, τ_1, τ_2) is an (i, j) - $T_{1/2}$ space then f is $D(i, j)$ - σ_k -continuous iff it is $\overline{D}(i, j)$ - σ_k -continuous.

(ii) If (X, τ_1, τ_2) is an (i, j) - T_u -space then f is τ_j - σ_k -continuous iff it is $\overline{D}(i, j)$ - σ_k -continuous.

Proof : (i) : Let $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $D(i, j)$ - σ_k -continuous then inverse image of every σ_k -closed set in Y is (i, j) - g -closed in X . Since every (i, j) - $\overline{g}$ -closed set is (i, j) - g -closed so inverse image of every σ_k -

closed set in Y is (i, j) - $\overline{g}$ -closed i.e. f is $\overline{D}(i, j)$ - σ_k -continuous.

Conversely $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $\overline{D}(i, j)$ - σ_k -continuous then by proposition (5.04 (i)), f is $D(i, j)$ - σ_k -continuous.

(ii) Same as (i).

Definition 5.18 : A map. $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is called $\overline{D}(i, j)$ - σ_k -irresolute if the inverse image of every σ_k - $\overline{g}$ -closed set in Y is (i, j) - $\overline{g}$ -closed set in X .

Proposition 5.19 : If $f : (X, \tau_1, \tau_2)$

$\rightarrow (Y, \sigma_1, \sigma_2)$ is $\overline{D}(i, j)$ - σ_k -irresolute then it is $\overline{D}(i, j)$ - σ_k -continuous but not conversely.

Example 5.20 : Let $X = Y = \{a, b, c\}$, $\tau_1 = \{\phi, \{a\}, \{b\}, \{a, b\}, X\}$, $\tau_2 = \{\phi, \{a\}, \{b, c\}, X\}$ and $\sigma_1 = \{\phi, \{a\}, Y\}$, $\sigma_2 = \{\phi, \{b\}, \{b, c\}, Y\}$. Define $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by identity mapping then f is $\overline{D}(1, 2)$ - σ_1 -continuous but not $\overline{D}(1, 2)$ - σ_1 -irresolute.

Proposition 5.21 : If $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $\overline{D}(i, j)$ - σ_k -continuous and (Y, σ_k) is $\overline{T}$ -space then f is $\overline{D}(i, j)$ - σ_k -irresolute.

Proof : Let $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $\overline{T}(i, j)$ - σ_k -continuous then inverse image of every σ_k -closed set in Y is (i, j) - $\overline{g}$ -closed in X . Since (Y, σ_k) is $\overline{T}$ -space so every σ_k - $\overline{g}$ -closed set is σ_k -closed i.e. inverse image of every σ_k - $\overline{g}$ -closed set is (i, j) - $\overline{g}$ -closed so f is (i, j) - $\overline{g}$ - σ_k -irresolute.

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